# FC SERIES COMPACT CONTROLLER S (PROGRAMMABLE, STEP OUTPUT TYPE)

## DATA SHEET

The Compact Controller S (programmable type) is a compact single-loop controller using a microprocessor. It accepts uniform signal, and signals from thermocouple and RTD (Resistance bulb) as input, and is equipped with abundant control and computation functions to allow composing a flexible system with a high cost/performance.

## FEATURES

1. Abundant control and computation functions

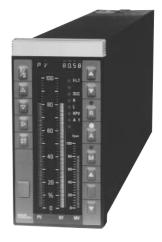
The controller has a variety of control and computation functions in addition to PID auto tuning, and also has a transmission function for data exchange with a host system.

2. Control and computation programming can be made at the site

Since the control and computation functions are built into wafers (functional units), an optimum program for the control object can be formed just by keying on the front panel.

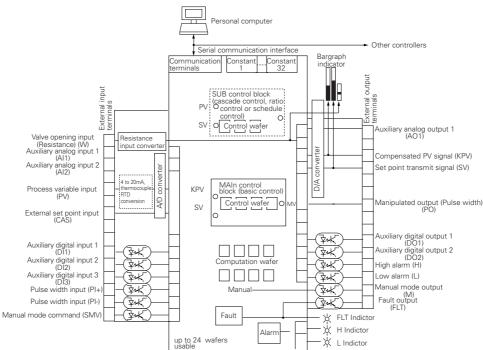
3. High reliability

LED's (red and green) are used for the bargraph indicator and also for the parameter indication (red), and a nonvolatile memory enables retaining the control and computation parameters even if power should be interrupted.



4. All operation is made from the front panel Operations such as parameter setting, auto/manual changeover are all made from the front panel.
5. Personal computer interface

Generic interface availability for personal computer (IBM PC-AT) for supervision, operation, support, maintenance, etc.



## FUNCTIONAL DIAGRAM

PNC2

## SPECIFICATIONS

### 1. Control functions

(1) PID control: Proportional band (P); 1.0 to 3276.7% Integration time (I); 0.1 to 3276.7 sec Derivative time (D); 0.0 to 900.0 sec PID auto tuning function (according to code specification)

#### Wafer system program:

The following kinds of control are possible by combining wafers (functional units) (Examples of control)

Cascade control, ratio control, program control, gain schedule control, etc.

#### Type of alarms:

PV high/low alarm	Determined by
PV change rate alarm	wafer connection
DV high/low alarm	Alarms are indicated with
	front panel lights

Control cycle: 0.2 sec (24 wafer type) 0.4 sec (48 wafer type)

## 2. Computation functions

#### (1) Wafer

The wafer is a functional unit software package containing control and computation functions needed for measurement and control. Combination of these wafers each having its own particular function enables composing a flexible system applicable to a wide range of control... from basic PID control up to complex advanced control. The PNC2 can accommodate up to 24/48 wafers.

The following kinds of wafers are prepared to allow selection according to the control purpose.

- I For control ....... PID control, ratio control, program control, gain scheduler, PID parameter setting
- ② For computation. Various computations possible by combining the wafers given in Table 1

#### (2) Internal input/output terminals

Various internal terminals are provided for external analog input/output, digital input/output and wafer connection.

## (3) Constants

Various parameters used in computation and control can be freely defined.

- 32 constants at 24 wafers
- 48 constants at 48 wafers <sup>J</sup>

#### Table 1 List of computation wafers

Wafer name	Kinds	Functional outline
Logical operation	6	Carries out AND, OR, NOT, EOR and a combination of these logical operations.
Arithmetic operation	5	Carries out a combination of addition, subtraction, multiplication and division.
Temperature/pressure compensation	1	Carries out temperature and pressure compensation through use of differential pressure, compensated pressure, proper temperature.
Linearize	3	Carries out segmented-line approximation with 15-segmented-line function.
Program control	4	Time schedule control by step or polygonal line approximation with 7 segments.
Flip-flop	1	RS flip-flop.
Pulse width integration	1	Adds the change of input at each basic cycle to the previous integrated value.
Selector	1	Compares two input values, and provides HIGH output (Large one), LOW output (Smaller one), and result of judgement on large/small.
Changeover	1	Selects input or output via a switch function. Analog hold circuit also provided.
Timer	1	Outputs on-delay, off-delay timer signal via start of input signal according to timer setting.
Absolute value/sign inversion	1	Carries out absolute value processing on input and outputs the result. Also judges the sigh (Positive, negative) of input value and outputs the result.
Square root extraction	1	Extracts square root of input value and outputs the result. Low input cutoff function equipped.
Lead, lag	1	Carries out lead/lag operation on the input and outputs the results. Used as analog filter function and for various compensations.
Limiter	1	Limits the input within the range of high/low limit settings, and outputs the result. Also outputs high/low limit alarm signal.
Ramp function	2	Outputs signal which changes in ramp from toward target value at the set full scale time. There are two of these wafersin minute unit and hour unit.
Analog averaging	1	Carries out sequential integration on input data, calculates the average value at each averaging time, and outputs the result.
Analog integration	1	Integrates the value obtained by multiplying the input data by a proportional constant, and outputs the result.
Pulse generation	1	Outputs a pulse at the set time interval.
Dead band	1	Adds dead band compensation to the input and outputs the result.
Pulse No. counter	1	Detects rise of pulse and counts the number of pulses.
Pulse No. output	1	Integrates the input signal and converts it to number of pulses for output.
Decoder	1	Decodes 2-bit pure binary input and outputs it to 4 terminals.
Moving average	2	Calculates moving average of input data and outputs the result.
Sample hold	1	Holds the input value according to sample signal (0/1) and continues the output.
Dead time	6	Usable for dead time compensation control etc. Data sampling can be done in 1 sec or 1 min units.
ON-OFF	1	Outputs ON-OFF signal with hysteresis versus the input.
Alarm	1	Compares the input and set value and outputs the judgement result.
Position type pulse width conversion	1	Performs output processing in time proportional PID control.

A variety of applications are possible through combination of wafers.

## 3. Input signals

(1) Process variable input signal: One input selectable from the following

Voltage input signal		1 to 5V DC	Input resistance $1M\Omega$ or more Allowable error $\pm 0.2\%/FS^*$
Current input signal		4 to 20mA DC	24V DC can be supplied to transmitter in case of AC power supply Allowable error ±0.2%/FS
Thermocouple input	'o   _	Types J:0 to 600°C K:0 to 1200°C E:0 to 800°C R:0 to 1600°C	10mV DC span or more; reference junction com- pensating function built in Allowable error ±0.5%/FS
Resistance bulb input		Pt100Ω (0°C) -50 to 500°C	50°C span or more Allowable error ±0.5%/FS

## (2) Analog input signal: 3 points

External set point	CAS	1 to 5V DC	Input resistance $1M\Omega$
Aux. analog input	Al1		or more, allowable error ±0.2%/FS
Aux. analog input	Al2		±0.2%/FS

CAS is usable as aux. analog input.

#### (3) Digital input signal: 4 points

Manual mode command	SMV	Contact input	ON 0V, OFF 24V
Aux. digital input			(Input current
Aux. digital input		isolation)	about 11mA/24V DC)
Aux. digital input	DI3		

#### (4) Pulse width input signal: 1 set

Pulse width	PI₊, PI₋	Contact input	ON 0V, OFF 24V
input signal		(Photocoupler	(Input current : about
		isolation)	11mA/24V DC)

#### (5) Valve opening input

	_	
Signal of valve	$W_{+}$	0 to 1.5k $\Omega$ potentio-meter
opening input	W <sub>0</sub>	or 1 to 5V DC input resistance
		$1M\Omega$ or more

#### 4. Output signals

#### (1) Manipulated output signal: 1 set

Pulse width output	PO_	Open collector output (Photocoupler isolation)	Output rating 30V DC 0.1A max.
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#### (2) Analog output signal: 3 points

Compensated PV signal	KPV	1 to 5V DC	Output resistance	
Set point transmit signal	SV		1 $\Omega$ or less, allowable error	
Aux. analog output	AO1		±0.2%/FS	
KPV and SV is usable as aux. analog output.				

#### (3) Digital output signal: 6 points

Fault output	FLT		Output rating
Manual mode output	M		30V DC 0.1A max.
High alarm output	Н		
Low alarm output	L		
Aux. digital output	DO1		
Aux. digital output	DO2		

H and L are usable as aux. digital output.

Note: \*FS.....full scale

## 5. Internal uniform data conversion

#### (1) Analog data

Standard	Minimum	Maximum
0.00 to 100.00%	-327.6%	327.67%

#### (2) Digital data

Input/output form	Data
ON (Contact closed)	0.01%
OFF (Contact open)	0.00%

### 6. Indication, setting, operation functions (1) Bargraph indication

Indication method	PV indicator	SV indicator	MV indicator	
Indication method	LED (Red)	LED (Green)	LED (Red)	
No. of segments	101 + 2	101 + 2	51 + 2	
Range	0 to 100% linear	0 to 100% linear	0 to 100% linear	
Resolution	1%/FS	1%/FS	2%/FS	
Scale length	100mm	100mm	50mm	
Indication mode	0 to 100% bargraph indication, 0 to 100% reverse bargraph indication, dot indication, -50 to 50% deviation indication			

#### (2) Operation mode indication Indication method:

LED (Red and green) Red; M, SCC

Green; A, R

#### (3) Numerical indication, setting

#### Indication method:

LED (Red), name in 3 digits+number in 5 digits (Negative sign included)

#### Indication contents:

Process variable (Engineering unit), set point (Engineering unit), high/low alarm values, PID parameters etc. Indication contents are selectable by F/S,

 $\bigtriangleup$ ,  $\bigtriangledown$  keys on front panel.

#### Setting method:

By use of F/S,  $\bigtriangleup$ ,  $\bigtriangledown$ ,  $\bigtriangledown$ ,  $\bigcirc$ , ST keys on front panel.

#### (4) SV setting function

#### Fixed value setting method:

By **A v** buttons on front panel. Setting speed; about 40 sec/FS

#### Remote setting method:

By external set point signal

(Voltage or pulse width input)

## (5) MV operating function

Manual operating method:

#### By ( , buttons on front panel.

#### (6) Operation mode changeover

By R/A/M pushbuttons on front panel.

$R \rightarrow A$ changeover		Balanceless bumpless	
A → R changeover	Voltage signal	Balance bumpless	
	Pulse width input	Balanceless bumpless	
A or R 🛨 M changeover		Balanceless bumpless	
*FS full scale			

## 7. Power failure processing function

Power failure detection:

Control stoppage at power failure detection

#### During power failure:

Operating parameters backed up by capacitor when power failure within 5 minutes.

Initial set point and manipulated output values, PID parameters etc. are stored in nonvolatile memory (lasts for 10 years or longer at ambient temperature of 50°C or less).

#### Power failure recovery time:

Initial or continuous start settable for power failure within 5 minutes. Recovery from power failure lasting longer than 5 minutes is done by initial.

\*Control mode at initialization is settable.

- M: Manual mode
- A: Automatic mode
- R: Remote mode
- SCC: SCC mode

### 8. Self-diagnosis functions

#### Computation/control circuit abnormality:

FLT indicator lights up, FLT contact output turns ON, and computation and control stop.

Manipulated output can be controlled manually at FLT (Soft manual).

## Input/output signal abnormality, manipulated output

deisconnection: FLT indicator lights up, FLT contact output turns ON, control stops, and manipulated output is held. Computation processing and output processing other than for manipulated output continue.

#### Fault contents indication:

Cause of fault is indicated numerically on numerical indicator of front panel.

## 9. Transmission functions

(1) Transmission items

## Supervisory items:

From PNA to host

Process variable, set point, manipulated output, deviation, operation mode, alarm information, fault information, PID parameters, various limiter values, constants, segmented line, analog input/output, digital input/output, control program (Wafer connecting information) etc.

#### Setting operation items:

From host to PNA

Set point, manipulated output, operation mode, PID parameters, various limiter values, constants, segmented line, control program (Wafer connecting information) etc.

#### (2) Transmission setting inhibit:

Parameter setting enable/inhibit can be designated by transmission from the host. Designation is done by  $\overline{\text{F/S}}$ ,

 $\bigtriangleup$ ,  $\bigtriangledown$ ,  $\triangleright$ , ST keys on the front panel.

(3) Transmission interface

CC data line or RS-422 interface selectable

- ① CC data line: Connected with transmission controller (PMN)
  - Interface: PMN and PNC; CC data line (RS-232C for PMN and host)
  - Transmission speed: 19.2 KBPS

No. of units connectable:

15 max. Transmission distance:

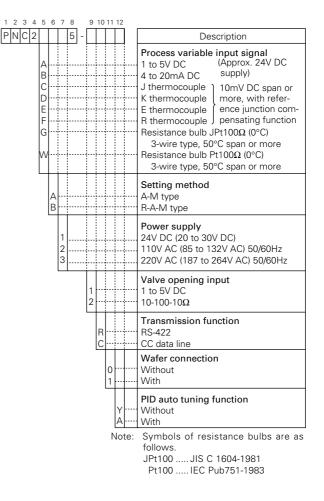
500m max.

- Transmission form:
- Multi-drop Cord format: 12 bit binary
- RS-422: Universal interface
- Transmission speed:
  - 2400, 4800, 9600 or 19200 BPS configurable
  - No. of units connectable:
  - 31 max.
  - Transmission distance:
  - 1km max.
  - Code format: One or two stop bits, parity EVEN/ODD/ NONE configurable.

#### 10. Other functions

Data protective function by means of pass code

## CODE SYMBOLS



## 11. Operating conditions

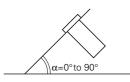
11. Operating	conditions			
Power supply:	Selectable from the following 3 types			
	24V DC (20 to 30V DC), 100V AC (85 to			
	132V/47 to 63Hz AC), 200V AC (187 to			
	264V/47 to 63Hz AC)			
Power consumption:				
	Approx. 12W (DC), 20VA (AC)			
Dielectric strength:				
	1500V AC for 1 minute			
Insulation resistance:				
	100M $\Omega$ or more at 500V DC			
Ambient temperature:				
	0 to 50°C			
Ambient humidity:				
	90%RH or less			
Enclosure:	Steel case			
Enclosure class:	Front IP65 (IEC 529)			
Nameplate:	100(H) $\times$ 70(W), white acrylic			
Dimensions:	144(H) x 72(W) x 391(D)mm, IEC (DIN)			
	standards			

Mass{weight}: Approx. 2.9kg

Mounting method:

Flush on indoor panel; vertical mounting is standard

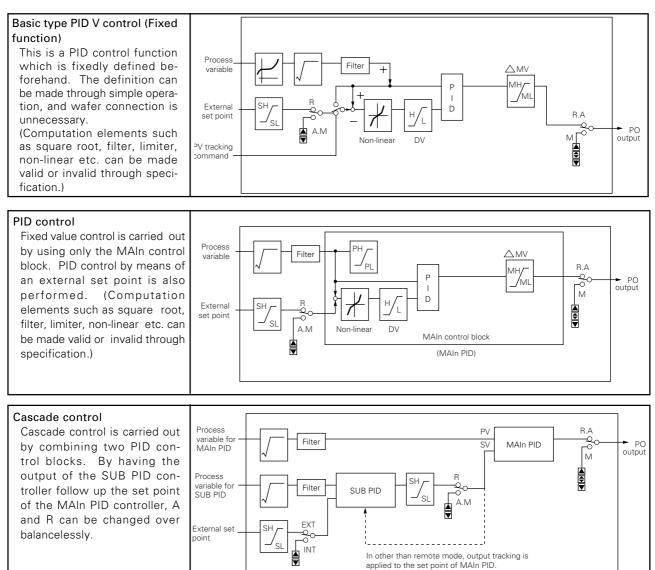
Mounting on tilted surface possible (Angle  $\alpha$ )



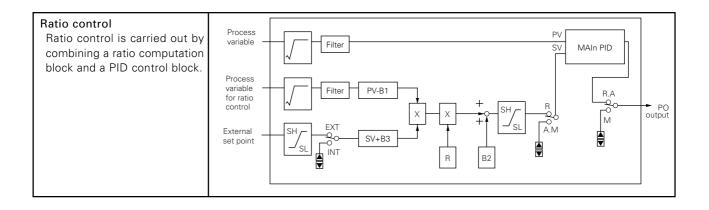
Finish color:Munsell N1.5 for front panel and caseRange of delivery:Controller and mounting bracketItem prepared separately:

Transmission cable (Type PNZ)

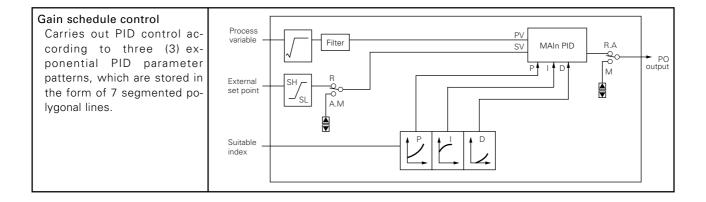
## VARIOUS CONTROL EXAMPLES



## PNC2

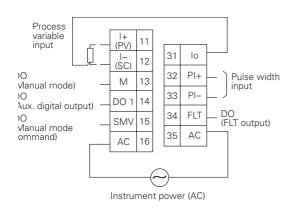


#### Program control Process variable By combining a program set-ΡV Filter MAIn PID ting block and a PID control SV R.A ћ., 90 М Program pattern ► PO output block, the set point is changed Output and controlled via a time func-Program R STOP 7 segments stop command tion. A.M A preset function is also pro-PRESET Preset command vided for starting program Time control from the present temperature in a furnace for control of heating or the like.



## EXTERNAL CONNECTION DIAGRAM

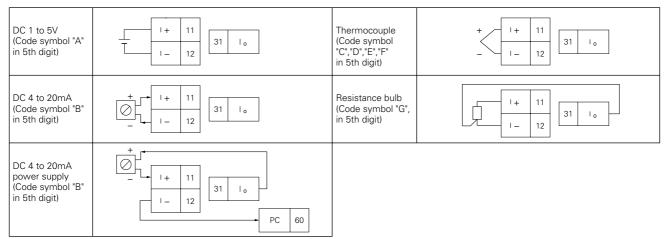
Block terminals (M4 screw)

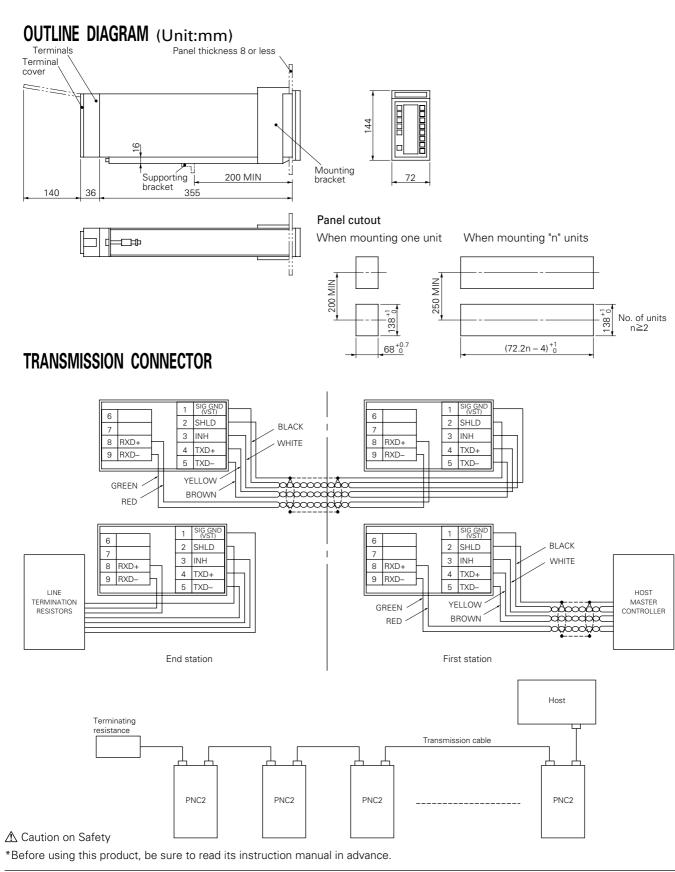


AO	、	KPV	51	71	CAS	
(Compensated PV signal	)		51		0/10	(External set point input)
(Set point transmit signa	I) —	SV	52	72	AI 1	Al (Aux. analog input)
AO (Aux. analog output)	_	AO 1	53	73	AI 2	AI (Aux. analog input)
WO		WO	54	74	W+	W+
(Bulb opening input)		000	54	74	vv+	(Bulb opening input)
AI, AO Common line	_	SC	55	75	W–	W-
PO	(					(Bulb opening input) AI, AO
(Pulse width output)	-	PO+	56	76	SC	(Common line)
	$\lfloor $	PO-	57	77	DO 2	
DO		10-	57		002	(Aux. digital output)
(High alarm output) DO	-	Н	58	78	DI 3	DI (Aux. digital input)
(Low alarm output)		1	59	79	DI 2	DI
		L	09	79	DIZ	(Aux. digital input)
Instrument power (DC 24V)	_	PC*	60	80	DI 1	DI
24V power for DI, DO.	-	PCD	61	81	VP*	(Aux. digital input) <u>+</u> Instrument power
24v power for DI, DO.	_	PCD	10	δI	VP^	(DC 24V)
Ground	Ē	G	62	82	VPD	+ 24V power for DI, DO

Note \* Symbols for AC power supply are VPO, PCO. Output is 24V DC (0.1A max.) approx.

## **TERMINAL CONNECTION OF PV INPUT**





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